

# Chapter 1

## "Some basics"

1) Natural units

2) Relativistic kinematics

- Lorentz transformations : 4-vector notation

- Energy momentum 4-vector

3) the elementary particle content of the SM

## 4) Natural units

In physics 3 independent dimensionfull quantities

Quantity	Dimension	Unit in IS
Mass	[M]	kg
Length	[L]	m
Time	[T]	s

The dimension of any other quantity is expressed as powers of these 3.

Quantity	Dimension	Unit in IS
Velocity	$[v] = \left[ \frac{L}{T} \right]$	m/s
Energy	$[E] = \left[ M \frac{L^2}{T^2} \right]$	$kg \frac{m^2}{s^2} = J$ (Joules)
Action	$[S] = [ET] = \left[ M \frac{L^2}{T} \right]$	$kg \frac{m^2}{s} = J \cdot s$

In particle physics we use as unit of energy the

$$eV \equiv 1.602 \times 10^{-19} J$$

Two universal constants relevant in particle physics

- speed of light

$$c \stackrel{IS}{\downarrow} = 2.999 \times 10^8 \text{ m/s}$$

- reduced Planck constant

$$\hbar = 1.055 \times 10^{-34} \text{ J s (action)}$$

$$= 6.582 \times 10^{-25} \text{ GeV s}$$

$$\uparrow$$

$$10^9 \text{ eV}$$

Most particles move with velocities of close to  $c$  and  
 for quantum systems actions are  $\sim \hbar$   
 So it is convenient to define a system of units  
 $\equiv$  natural units in which velocities are given  
 in units of  $c$  and actions in units of  $\hbar$

$\Rightarrow$  In NU Speed of light = 1  
 Planck reduced const = 1

In NU one can express any quantity in units  
 of a unique dimension full quantity. We use  
 energy and express any quantity in power of eV

Quantities

$$\hbar \stackrel{\text{IS}}{\downarrow} = 6.58 \times 10^{-25} \text{ GeVs} \stackrel{\text{in NU}}{=} 1 \Rightarrow 1\text{s} = 1.52 \times 10^{15} \text{ eV}^{-1}$$

$$\hbar c = 1.97 \times 10^{-16} \text{ GeV} \stackrel{\text{in NU}}{=} 1 \Rightarrow 1\text{m} = 508 \times 10^6 \text{ eV}^{-1}$$

$\Rightarrow$  we express time and length in  $\text{eV}^{-1}$

$$\frac{\hbar}{c^2} \stackrel{\text{IS}}{\downarrow} = \frac{1}{8.47 \times 10^{50}} \frac{\text{kg}}{\text{s}} \stackrel{\text{in NU}}{=} 1 \Rightarrow 1\text{kg} = 8.47 \times 10^{50} \text{ s}^{-1}$$

$$= 5.57 \times 10^{25} \text{ eV}$$

express mass in multiples of eV  
 We will use NU and do not write " $c_s$ " nor " $\hbar s$ "  
 in our eqs.

# 2) Relativistic Kinematics (Griffiths chapter 3 for details)

## 2.1) Lorentz transformation

Relativity principle  $\equiv$  same laws of physics apply in any inertial system (inertial  $\equiv$  moving at constant velocity)  $\Rightarrow$  light (em waves) must travel at same speed in any inertial system

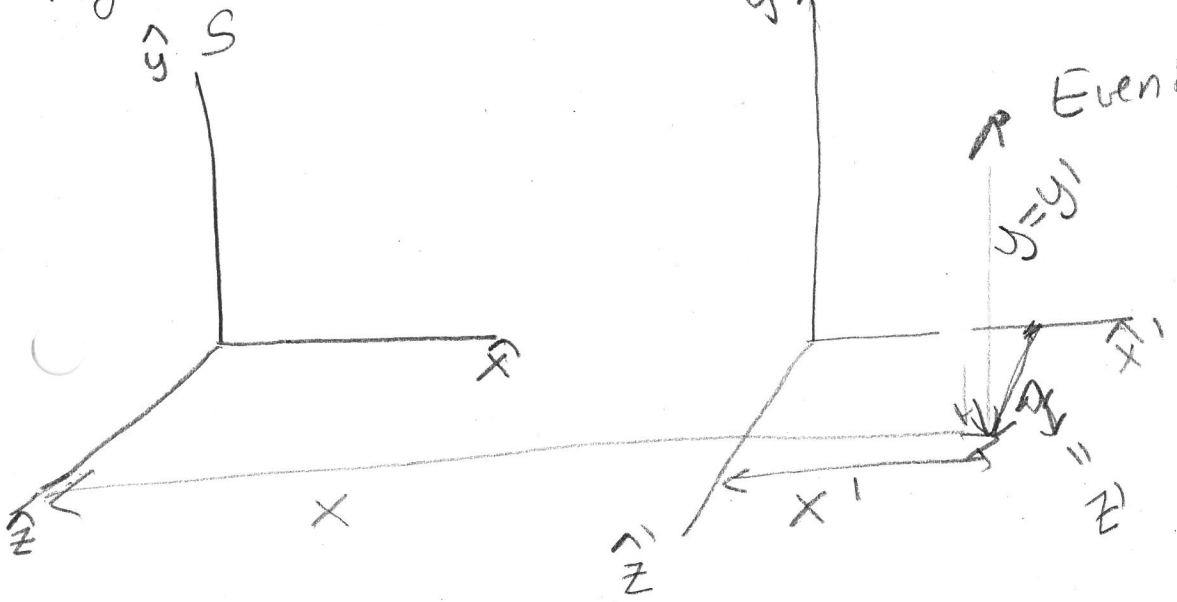
Take 2 systems of coordinates

- S with spatial coordinates  $(x, y, z)$  and time coordinate  $t$
- S' " " " "  $(x', y', z')$  " " " "  $t'$

S' is moving wrt S at velocity  $\vec{v} = v \hat{x}$

At  $t=t'=0$   $x=x'=y=y'=z=z'=0$

After some time



an event occurs at  $(x', y', z')$  at time  $t'$  at S'

Event In S' it is seen in  $(x', y', z')$  at  $t'$

At  $S'$  the event is observed at  $x', y', z'$ , at time  $t'$

with

$$x' = \gamma(x - vt) \equiv \gamma(x - \beta ct)$$

$\downarrow$   
NO

$$y' = y$$

$$z' = z$$

$$t' = \gamma(t - \frac{v}{c^2}x) \equiv \gamma(t - \beta \frac{x}{c})$$

with

$$\beta = \frac{v}{c} < 1 \quad \gamma = \frac{1}{\sqrt{1-\beta^2}} \geq 1$$

when  $\beta \rightarrow 1 \quad \gamma \rightarrow \infty$

$\equiv$  Lorentz transf

or equivalently

$$x = \gamma(x' + \beta ct')$$

$$y = y'$$

$$z = z'$$

$$t = \gamma(t' + \beta \frac{x'}{c})$$

Most ubiquitous consequences in particle physics

- time dilatation: if at rest ( $S'$ ) a particle lives has a lifetime  $\tau \equiv t'_2 - t'_1$  in a system in which it is moving with velocity  $\beta^{(S)}$  it lives a time

$$t_2 - t_1 \equiv \Delta t = \gamma[\tau + \beta(x'_2 - x'_1)] = \gamma\tau > \tau$$

$\begin{matrix} \text{"at rest in } S' \end{matrix}$

For ultra relativistic particles  $\beta \approx 1 \quad \Delta t \gg \tau$

So in  $S'$  the particle travels a distance

$$L = \beta \Delta t = \beta \gamma z \gg \beta z \leftarrow \begin{matrix} \text{non} \\ \text{relativistic estimate} \end{matrix}$$

- Length contraction: an object that at rest ( $S$ )

measures  $L = x_2 - x_1$  in a system in which it is moving at velocity  $\beta$  ( $S'$ ) is seen (both extremes are seen at same time so  $t'_1 = t'_2$ ) with length

$$L' = x'_2 - x'_1 \quad \text{with} \quad \begin{matrix} x_1 = \gamma(x'_1 + \beta t'_1) \\ x_2 = \gamma(x'_2 + \beta t'_2) \end{matrix} \Rightarrow L = \gamma L'$$

$$\Rightarrow L' = \frac{L}{\gamma} \ll L \quad \text{contracted.}$$

So that is why the distance traveled in  $S$

$$L = \beta \Delta t = \beta \gamma z$$

is seen much shorter at the rest frame of the particle ( $S'$ )  $L' = \frac{\beta z \gamma}{\gamma} = \beta z$

No time  
inclass

To simplify notation we introduce 4-vectors  
 the contravariant position-time 4 vector with  
 coordinates  $x^\mu$  ← *supper index*  
 $\mu = 0, 1, 2, 3$

$x^0 = ct \equiv t$ ,  $x^1 = x$ ,  $x^2 = y$ ,  $x^3 = z$

which we write as a column 4-vector ← *my notation for 3-vector*

~~$X$~~  =  $\begin{pmatrix} x^0 \\ x^1 \\ x^2 \\ x^3 \end{pmatrix} \equiv \begin{pmatrix} t \\ x \\ y \\ z \end{pmatrix} \equiv \begin{pmatrix} x^0 \\ \vec{x} \end{pmatrix}$  with  $\vec{x} \equiv \begin{pmatrix} x \\ y \\ z \end{pmatrix}$

In this notation a Lorentz transformation can  
 be written in matrix form

$$\begin{pmatrix} x'^0 \\ x'^1 \\ x'^2 \\ x'^3 \end{pmatrix} = \begin{pmatrix} \gamma & -\gamma\beta & 0 & 0 \\ -\gamma\beta & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x^0 \\ x^1 \\ x^2 \\ x^3 \end{pmatrix}$$

$4 \times 4$  matrix  $\Lambda$

which can be written as

$x'^\mu = \sum_{\nu=0}^3 \Lambda^\mu_\nu x^\nu \equiv \Lambda^\mu_\nu x^\nu$

↓ Einstein's convention  
 repeated upper  
 lower index  
 are assumed  
 to be summed

We define the covariant position-time 4-vector

$$X_\mu = \sum_{\nu=0}^3 g_{\mu\nu} X^\nu \equiv g_{\mu\nu} X^\nu$$

↑  
lower index

where  $g_{\mu\nu} \equiv$  metric tensor which in matrix form

$$g \equiv \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix} \Rightarrow X_0 = X^0, X_1 = -X^1, X_2 = -X^2, X_3 = -X^3$$

and we write the covariant 4-vector as line 4-vector

$$(X_0, X_1, X_2, X_3) \equiv (X_0, -X^1, -X^2, -X^3)$$

The 4-norm of the space-time 4-vector

$$\begin{aligned} (X)^2 &\equiv X^0^2 - X^1^2 - X^2^2 - X^3^2 \equiv X^0 X_0 + X^1 X_1 + X^2 X_2 + X^3 X_3 = X^\mu X_\mu \\ &= X_\mu X^\mu \equiv X'^\mu X'_\mu \quad (\text{check}) \end{aligned}$$

So the norm of the 4-vector is invariant under a Lorentz transformation



Lorent group is the group of transformations which leave the 4-norm invariant

It includes

- boost of velocity  $\vec{\beta}$
- rotations in 3 dimension
- Parity  $\vec{x}' = -\vec{x}$  ,  $x^{0'} = x^0$
- Time reversal  $\vec{x}' = \vec{x}$  ,  $x^{0'} = -x^0$

3x3 rotation matrix

$$\vec{x}' = \mathcal{R}_{3 \times 3} \vec{x} \quad A_{\text{rot}} \begin{pmatrix} 1 \\ \vdots \\ 1 \end{pmatrix}$$

$$\Lambda_{\text{Par}} = \begin{pmatrix} 1 & & & \\ & -1 & & \\ & & -1 & \\ & & & -1 \end{pmatrix}$$

$$\Lambda_{\text{TR}} = \begin{pmatrix} -1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{pmatrix}$$

We define a contravariant 4-vector "a" a 4 dimensional column object

$$\begin{pmatrix} a^0 \\ a^1 \\ a^2 \\ a^3 \end{pmatrix}$$

which under Lorent transf transforms as

$$a'^{\mu} = \Lambda^{\mu}_{\nu} a^{\nu}$$

and the corresponding covariant 4-vector

$$a_{\nu} = g_{\mu\nu} a^{\nu}$$

An the scalar product of 4-vecs "a", "b" is invariant under Lorent transf.

$$a \cdot b \equiv a^0 b^0 - a^1 b^1 - a^2 b^2 - a^3 b^3$$

$$= a^0 b_0 + a^1 b_1 + a^2 b_2 + a^3 b_3 \equiv a^{\mu} b_{\mu} = a_{\mu} b^{\mu}$$

### 3.2 Energy - momentum 4-vector

In special relativity motion of a particle of mass  $m$

and velocity  $\vec{\beta} = \frac{d\vec{x}}{dx^0}$  is characterized by

- its 3 momentum  $\vec{p} = m \gamma \vec{\beta} = \vec{\beta} E$   
 - its Energy  $E = m\gamma$

$$\gamma = \frac{1}{\sqrt{1-\beta^2}} \quad \beta = |\vec{\beta}| \Rightarrow \beta^2 = 1 - \frac{1}{\gamma^2}$$

$$\Rightarrow |\vec{p}|^2 = \beta^2 \gamma^2 m^2 = m^2 \gamma^2 - m^2 = E^2 - m^2 \Rightarrow E^2 = |\vec{p}|^2 + m^2$$

Since  $\begin{pmatrix} x^0 \\ \vec{x} \end{pmatrix}$  is a 4-vector  $\Rightarrow \begin{pmatrix} m\gamma \\ m\vec{\beta} = m \frac{d\vec{x}}{dx^0} \end{pmatrix}$  is a 4-vector

We call it the Energy - momentum 4-vector  $P$

$$\begin{pmatrix} P^0 = E = \sqrt{|\vec{p}|^2 + m^2} \\ \vec{p} \end{pmatrix}$$

Its 4-norm

$$P^2 = P^0^2 - |\vec{p}|^2 = E^2 - |\vec{p}|^2 = m^2 \quad \text{😊}$$

$\Rightarrow$  mass is invariant under Lorentz transform  $\Rightarrow$  it is the same in any inertial system.

A particle with  $m=0 \Rightarrow E=|\vec{p}| \equiv \beta E \rightarrow \beta=1$   
 $\Rightarrow$  moves at speed of light

Invariance under translations  $\Rightarrow$  in any physical process the total Energy-momentum 4-vector is conserved.

So for any process,

$N$  initial particles  $\longrightarrow$   $M$  final particles

with 4-momenta

$$P_i^{ini} = \begin{pmatrix} E_i^{ini} = \sqrt{|\vec{p}_i^{ini}|^2 + m_i^2} \\ \vec{p}_i^{ini} \end{pmatrix}$$

$i=1 \dots N$

$$P_d^{fin} = \begin{pmatrix} E_d^{fin} = \sqrt{|\vec{p}_d^{fin}|^2 + m_d^2} \\ \vec{p}_d^{fin} \end{pmatrix}$$

$j=1 \dots M$

$$P_{TOT}^{ini} = \begin{pmatrix} \sum_{i=1}^N E_i^{ini} \\ \sum_{i=1}^N \vec{p}_i^{ini} \end{pmatrix} = P_{TOT}^{fin} = \begin{pmatrix} \sum_{j=1}^M E_d^{fin} \\ \sum_{j=1}^M \vec{p}_d^{fin} \end{pmatrix} \leftarrow 4 \text{ equations}$$

$\Rightarrow$  If we know the energy and 3-momentum of all initial particles  $\Rightarrow$  relations among energy and 3-momenta (ie their directions) of final particles  $\equiv$  kinematic constraints

# Examples

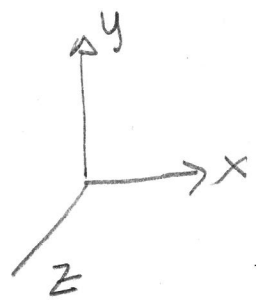
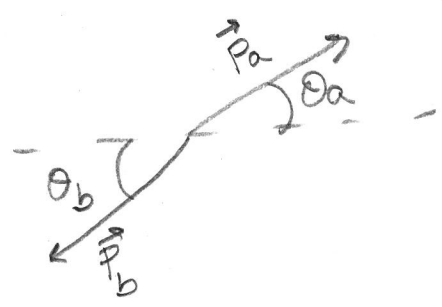
(1)

Particle A of mass  $M$  decays at rest into two particles with mass  $m_a$  and  $m_b$

Initial



Final



$$P_{TOT}^{int} = \begin{pmatrix} E_A^{int} = M \\ \vec{P}_A^{int} = \vec{0} \end{pmatrix}$$

at rest

$$P_a^{fin} = \begin{pmatrix} E_a = \sqrt{|\vec{p}_a|^2 + m_a^2} \\ \vec{p}_a \end{pmatrix}$$

$$P_b^{fin} = \begin{pmatrix} E_b = \sqrt{|\vec{p}_b|^2 + m_b^2} \\ \vec{p}_b \end{pmatrix}$$

$$(1) \quad E_A = M = E_a + E_b = \sqrt{|\vec{p}_a|^2 + m_a^2} + \sqrt{|\vec{p}_b|^2 + m_b^2}$$

$$(2) \quad 0 = \vec{p}_a + \vec{p}_b \Rightarrow \vec{p}_a = -\vec{p}_b \Rightarrow \text{a, b produced back to back}$$

$$\Rightarrow \theta_b = \pi + \theta_a \equiv \theta_{AR}$$

$$\Rightarrow |\vec{p}_a| = |\vec{p}_b| \equiv P_f$$

$$(1) \Rightarrow M = \sqrt{P_f^2 + m_a^2} + \sqrt{P_f^2 + m_b^2} \Rightarrow P_f = \frac{\sqrt{(M - (m_a + m_b))^2 (M - (m_a - m_b))^2}}{2M}$$

$$\Rightarrow E_a = \sqrt{P_f^2 + m_a^2} = \frac{M^2 + m_a^2 - m_b^2}{2M}$$

$$E_b = \sqrt{P_f^2 + m_b^2} = \frac{M^2 + m_b^2 - m_a^2}{2M}$$

Notice that if  $M < (m_a + m_b) \Rightarrow P_f$  imaginary  $\equiv$

decay not possible

Lets look at same process in another frame in which

A is moving at  $\vec{\beta} = +\beta \hat{x}$ . Lets call this frame AF

We can obtain  $P_{ab}^{AF}$  from (and previous AR)  $\uparrow$  flight

$P_{ab}^{AR}$  using that these are 4-vectors so under the Lorentz transf from AR to AF they

are

$$\begin{pmatrix} E_a^{AF} \\ P_{ax}^{AF} \end{pmatrix} = \begin{pmatrix} \gamma & \gamma\beta \\ \gamma\beta & \gamma \end{pmatrix} \begin{pmatrix} E_a^{AR} \\ P_{ax}^{AR} \end{pmatrix}$$

$$P_{ay}^{AF} = P_{ax}^{AR} = P_p \sin \theta_{AR}$$

$$P_{az}^{AF} = P_{az}^{AR} = 0$$

$$P_p \cos \theta_{AR}$$

So  $E_a^{AF} = \gamma (E_a^{AR} + \beta P_p \cos \theta_{AR})$

for  $b \cos \theta_{AR} \rightarrow -\cos \theta_{AR}$   
 $\sin \theta_{AR} \rightarrow -\sin \theta_{AR}$

$$P_{ax}^{AF} = \gamma (P_{ax}^{AR} + \beta E_a^{AR})$$

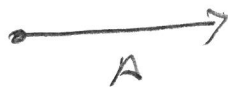
So  $\tan \theta_a^{AF} = \frac{P_{ay}^{AF}}{P_{ax}^{AF}} = \frac{P_p \sin \theta}{\gamma (P_p \cos \theta + \beta E_a^{AR})}$

for  $m_a, m_b \ll M$

$$\tan \theta_A^{AF} \approx \frac{\sin \theta}{\gamma (\cos \theta + \beta)} \ll \tan \theta$$

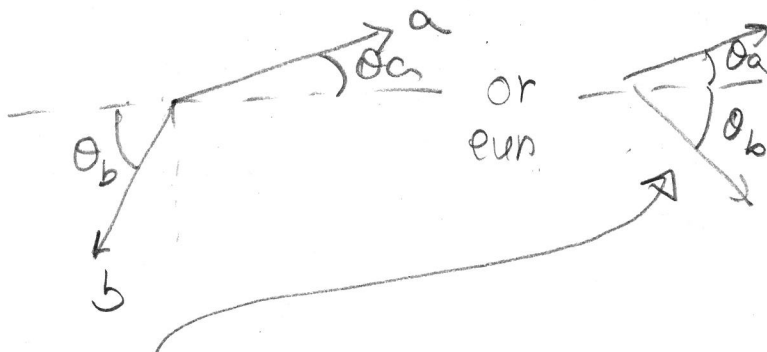
$\Rightarrow$  emission closer to A moving direction

Graphically in AF  
Initial



Final

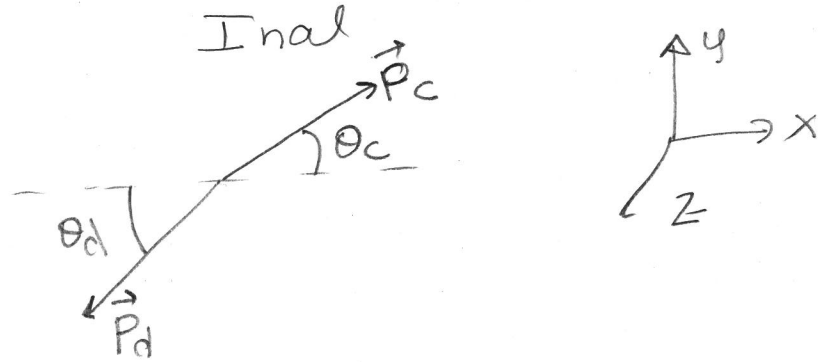
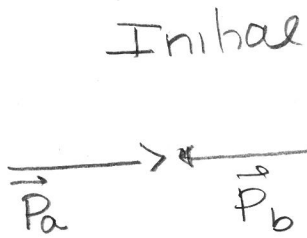
Final



If  $\cos \theta_{AR} > \frac{\beta E_b^{AR}}{P_f} \Rightarrow \tan \theta_b^{AF} < 0$

Example 2 ;  $a+b \rightarrow c+d$  (2 to 2 scattering)

• In COM



Definition of COM  $\vec{p}_a + \vec{p}_b = 0 \Rightarrow |\vec{p}_a| = |\vec{p}_b| \equiv P_{in}$   
 conservation of energy-momentum  $\Rightarrow \vec{p}_c + \vec{p}_d = \vec{p}_a + \vec{p}_b = 0$   
 $\Rightarrow \vec{p}_c = -\vec{p}_d \Rightarrow$  back to back  
 $|\vec{p}_d| = |\vec{p}_c| \equiv P_f$

Let us define the mandelstam variables

4-vector  
 $S = (\vec{p}_a + \vec{p}_b)^2 = (\vec{p}_c + \vec{p}_d)^2 = (E_a + E_b)^2 - |\vec{p}_a + \vec{p}_b|^2 = (E_c + E_d)^2 - |\vec{p}_c + \vec{p}_d|^2$

$S \equiv$  norm of a 4-vector  $\Rightarrow$  same value in any inertial ref frame

In COM  $S = (E_a + E_b)^2 = (E_c + E_d)^2 \equiv$  energy available for collision

$= (\sqrt{P_{in}^2 + m_a^2} + \sqrt{P_{in}^2 + m_b^2}) \rightarrow P_{in} = \frac{\sqrt{(S - (m_a + m_b)^2)(S - (m_a - m_b)^2)}}{2\sqrt{S}}$

$= (\sqrt{P_f^2 + m_c^2} + \sqrt{P_f^2 + m_d^2}) \rightarrow P_f = \frac{\sqrt{(S - (m_c + m_d)^2)(S - (m_c - m_d)^2)}}{2\sqrt{S}}$

For  $m_a, m_c, m_d, m_b \ll \sqrt{s}$  we get

$$P_{in} \approx P_f \approx \frac{\sqrt{s}}{2}$$

Same as 2-body decay of a mass

$$M = \sqrt{s}$$

$$\text{and } E_c = \frac{1}{2\sqrt{s}} (s - m_d^2 + m_c^2) \rightarrow \frac{\sqrt{s}}{2}$$

$$E_d = \frac{1}{2\sqrt{s}} (s - m_c^2 + m_d^2) \rightarrow \frac{\sqrt{s}}{2}$$

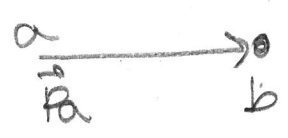
So if we want to produce some final state with mass  $m_{fin}$  [in this case  $m_{fin} = (m_c + m_d)$  but it works for any number of particles] we need

$$\sqrt{s} \geq m_{fin} \Rightarrow E_a = E_b = \frac{m_{fin}}{2}$$

(take  $m_a, m_b \ll \sqrt{s}$ )

(otherwise  $P_f$  is imaginary)

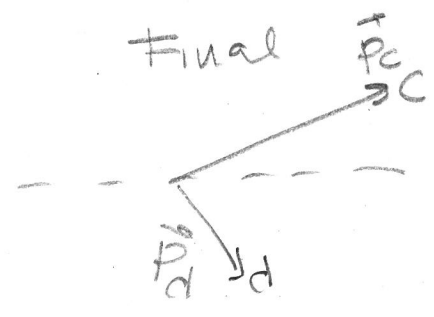
Let's look at process in LAB frame where 'b' is at rest



In LAB

$$E_b^{LAB} = m_b$$

$$\vec{p}_b^{LAB} = 0$$



$$s = (E_a^{LAB} + E_b^{LAB})^2 - (\vec{p}_a + \vec{p}_b^{LAB})^2 = E_a^2 - |\vec{p}_a|^2 + m_b^2 + 2E_a m_b$$

$$\Rightarrow s > m_{fin}^2 \Rightarrow E_a^L > \frac{1}{2m_b} (m_{fin}^2 + m_a^2 - m_b^2) \approx \frac{m_{fin}^2}{2m_b}$$

$m_a, m_b \ll m_{fin}$



### 3) Elementary particles of the SM

Matter is composed of fermions (spin  $\frac{1}{2}$  particles) which we classify in two groups

- quarks (which are bounded inside nucleus)
- leptons which are not

They come in 3 generations each one with 2 type of quarks and 2 type of leptons

	1st gen	2nd Gen	3rd Gen	Q	B	L
Quarks	up (u)	charm (c)	top (t)	$\frac{2}{3}$	$\frac{1}{3}$	0
	down (d)	strange (s)	bottom (b)	$-\frac{1}{3}$	$\frac{1}{3}$	0
Leptons	electron ( $e^-$ )	muon ( $\mu^-$ )	tau ( $\tau^-$ )	-1	0	1
	electron neutrino ( $\nu_e$ )	muon neutrino ( $\nu_\mu$ )	tau neutrino ( $\nu_\tau$ )	0	0	1

$Q \equiv$  electric charge in units of abs. value of electron charge "e"

$B \equiv$  baryon # quantum #

$L \equiv$  lepton # " #

$m_t > m_c > m_u ; m_b > m_s > m_d ; m_\tau > m_\mu > m_e$

B and Q are conserved in Nature as far as we tested  
L conservation is an open question. In SM L is conserved

Special relativity + Quantum mechanics  $\Rightarrow$   
for each particle there must be an antiparticle  
with same mass and spin but opposite Q, B, L

For example for 1st generation

		Q	L	B
antiquark	$\bar{u}$	$-\frac{2}{3}$	0	$-\frac{1}{3}$
"	$\bar{d}$	$\frac{1}{3}$	0	$-\frac{1}{3}$
positron	$e^+$	1	-1	0
electron	$\bar{\nu}$	0	-1	0
antineutrino				

Quarks are never observed as free states. They are always in bound states of 2 types

- Mesons  $\equiv (q \bar{q}') \Rightarrow B=0$  and spin is integer  
 i.e.  $\pi^\pm, \pi^0$  (pions),  $K^\pm, K^0$  (kaons)

- Baryons  $\equiv (qq'q'') \Rightarrow B=\frac{1}{2}$  and spin is half-integer

Interactions between these fermions are mediated by spin 1 particles  $\equiv$  gauge bosons  
 (= vector particles)

In SM there are 3 types of interactions

Interaction	Gauge boson	Q
electromagnetic	photon ( $\gamma$ )	0
strong	gluon ( $g$ )	0
weak	Z boson ( $Z$ )	0
	W " ( $W^\pm$ )	$\pm 1$

all have  $B=L=0$

In addition the model contains a particle (19)  
of spin zero (scalar)  $\equiv$  Higgs boson ( $h$ ).

In quantum mechanics we describe the state and evolution of a system by its wave function.

In relativistic quantum mechanics  $\equiv$  Quantum Field Theory  
the wave functions are substituted by fields which are operators acting on the Hilbert space of states.

The form and properties of the field representing a particle depends on its spin  $\Rightarrow$  chapter 2