

# PHY682 Special Topics in Solid-State Physics: Quantum Information Science

Lecture time: 2:40-4:00PM Monday & Wednesday

Today 9/21:

1. Will discuss Grover's algorithm
2. Next Week 5's topics: VQE, QAOA, Hybrid Q-Classical Neural Network, Application to Molecules

# Comments: Clifford gates and Gottesman-Knill no go theorem\*

- Clifford gates  $U_C$  are those that transform a Pauli product  $\sigma$  to another Pauli product operator  $\sigma'$ :

$$U_C \sigma U_C^\dagger = \sigma'$$

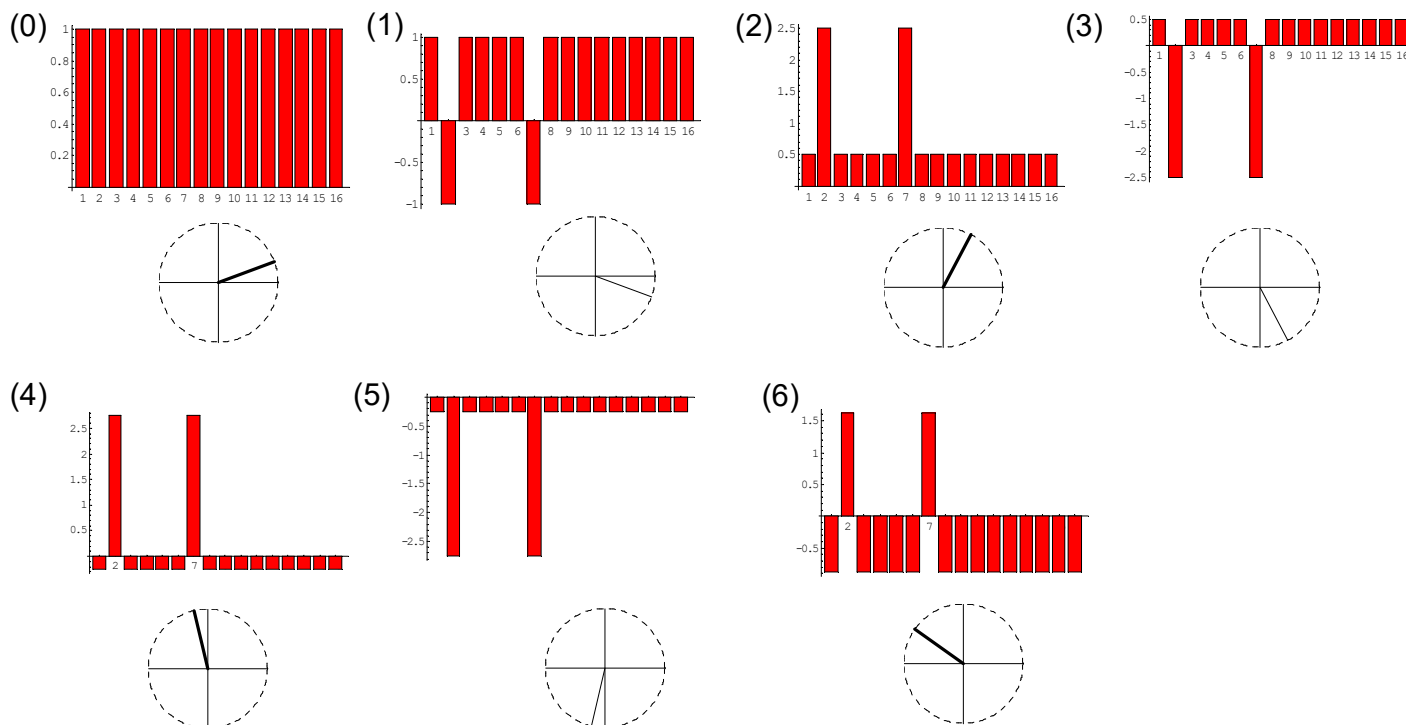
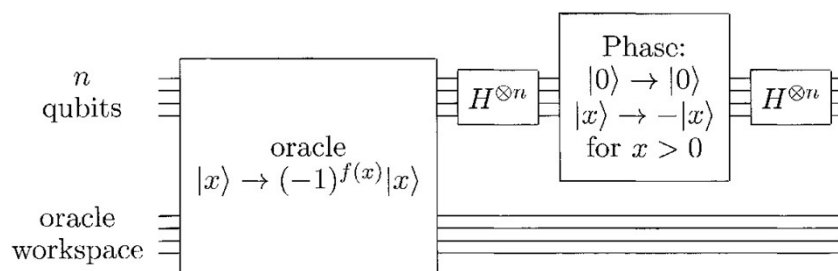
- Theorem 10.7: (Gottesman–Knill theorem) Suppose a quantum computation is performed which involves only the following elements: **state preparations in the computational basis, Hadamard gates, phase gates, controlled-NOT gates, Pauli gates, and measurements of observables in the Pauli group** (which includes measurement in the computational basis as a special case), together with the possibility of classical control conditioned on the outcome of such measurements.
- Such a computation may be efficiently simulated on a classical computer.

# Quick overview of Grover searching

Perform iteration:

- (i) Sign on marked targets
- (ii) Reflection w.r.t mean

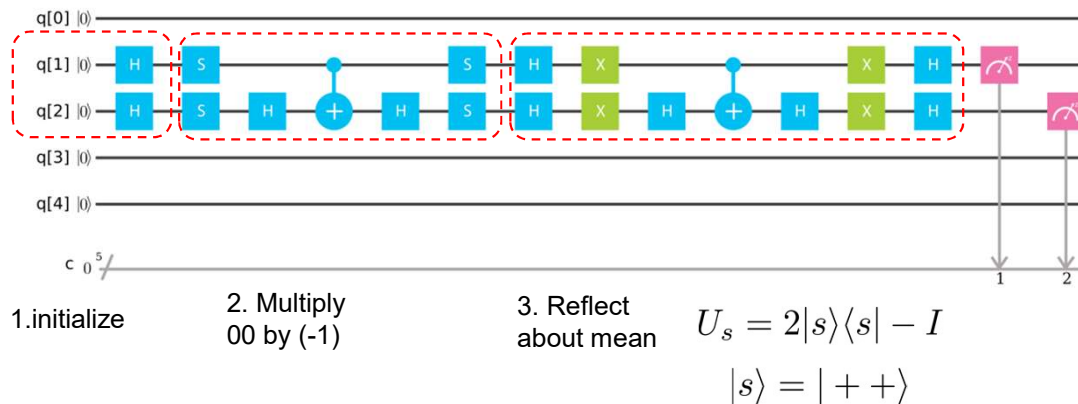
Suppose: items 2 and 7 marked



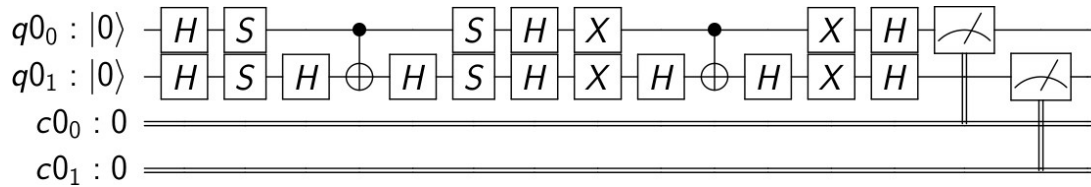
# One-step Grover

4 items (use 2 qubits) with marked item 00

- Web-based interface:



- Can use python codes (on right) and draw circuit:



```
q = QuantumRegister(2)
c = ClassicalRegister(2)
qc = QuantumCircuit(q, c)
```

```
# initialize
qc.h(q[0])
qc.h(q[1])
```

```
# mark item 0 (or  $|00\rangle$ )
qc.s(q[0])
qc.s(q[1])
qc.h(q[1])
qc.cx(q[0], q[1])
qc.h(q[1])
qc.s(q[0])
qc.s(q[1])
```

```
# apply reflection around average
qc.h(q[0])
qc.h(q[1])
qc.x(q[0])
qc.x(q[1])
```

```
qc.h(q[1])
qc.cx(q[0], q[1])
qc.h(q[1])
```

```
qc.x(q[0])
qc.x(q[1])
qc.h(q[0])
qc.h(q[1])
```

```
# measure
qc.measure(q, c)
```

See IBM Q userguide or my IPython Notebook:

[Note this is a very old notebook]

<https://nbviewer.jupyter.org/url/insti.physics.sunysb.edu/~twei/Notebook/GroverExample.ipynb>

# Analysis of one Grover step

(i) Sign on marked targets  
[equivalent to reflection w.r.t. the unmarked "plane"]

$$\hat{O}_f = \sum_x (-1)^{f(x)} |x\rangle\langle x| = I - 2 \sum_{x \in \text{marked}} |x\rangle\langle x|$$

(ii) Reflection w.r.t mean

$$U_s = 2|s\rangle\langle s| - I = H^{\otimes n} (2|0\dots 0\rangle\langle 0\dots 0| - I) H^{\otimes n}$$

$$|s\rangle = |++\dots+\rangle = \frac{1}{\sqrt{N=2^n}} \sum_{x=0}^{2^n-1} |x\rangle$$

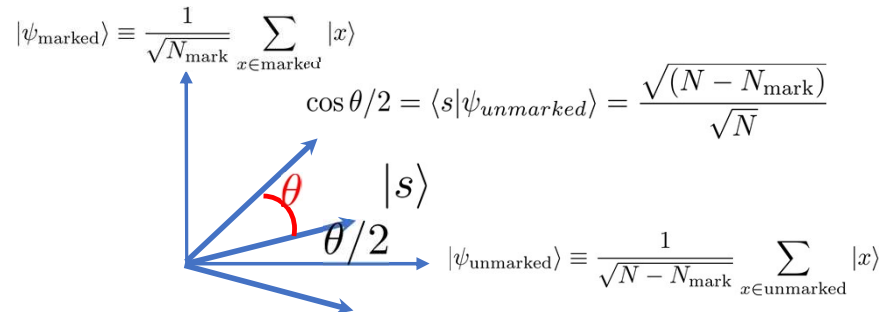
$$|\alpha\rangle \equiv \sum_k \alpha_k |k\rangle \longrightarrow 2|s\rangle\langle s|\alpha\rangle - |\alpha\rangle \quad \alpha_k \longrightarrow 2\frac{1}{N} \sum_j \alpha_j - \alpha_k = 2\langle\alpha\rangle - \alpha_k$$

□ One Grover iteration is a unitary operation that is equivalent to a rotation:

$$\hat{G} \equiv U_s \hat{O}_f$$

with the angle satisfying

$$\sin \theta = 2 \frac{\sqrt{N_{\text{mark}}(N - N_{\text{mark}})}}{N}$$



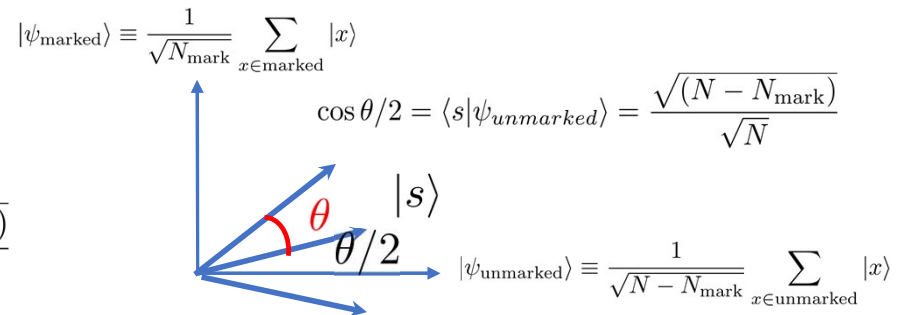
# Time complexity of Grover Algorithm

- One Grover iteration is a unitary operation that is equivalent to a rotation:

$$\hat{G} \equiv U_s \hat{O}_f$$

with the angle satisfying

$$\sin \theta = 2 \frac{\sqrt{N_{\text{mark}}(N - N_{\text{mark}})}}{N}$$



- Assume number of marked items smaller than  $N/2$ , and approximate

$$\theta \approx 2 \frac{\sqrt{N_{\text{mark}}(N - N_{\text{mark}})}}{N}$$

→ Number of iterations to reach an angle  $\pi/2$ :

$$N_{\text{iter}} \theta + \frac{\theta}{2} \approx \frac{\pi}{2} \quad N_{\text{iter}} \approx \frac{\pi}{2\theta} - \frac{1}{2} \approx \left\lceil \frac{1}{4} \sqrt{\frac{N}{N_{\text{mark}}}} \right\rceil$$

→ For  $N=4$ , only one marked item:  $\theta=\pi/3$ , one iteration reaches the target with probability 1

# What if number of marked items is unknown?

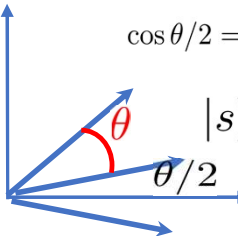
- One Grover iteration is a unitary operation that is equivalent to a rotation:

$$\hat{G} \equiv U_s \hat{O}_f$$

with the angle satisfying

$$\sin \theta = 2 \frac{\sqrt{N_{\text{mark}}(N - N_{\text{mark}})}}{N}$$

$$|\psi_{\text{marked}}\rangle \equiv \frac{1}{\sqrt{N_{\text{mark}}}} \sum_{x \in \text{marked}} |x\rangle$$

$$\cos \theta/2 = \langle s | \psi_{\text{unmarked}} \rangle = \frac{\sqrt{(N - N_{\text{mark}})}}{\sqrt{N}}$$


$$|\psi_{\text{unmarked}}\rangle \equiv \frac{1}{\sqrt{N - N_{\text{mark}}}} \sum_{x \in \text{unmarked}} |x\rangle$$

- Need to estimate  $\theta$  first, using the quantum phase estimation (later lecture)

→ Grover operator has two eigenvalues  $e^{\pm i\theta}$



# Generalization: Amplitude amplification\*

- Recall one Grover:

$$\hat{G} \equiv U_s \hat{O}_f$$

$$= H^{\otimes n} U_{|0\rangle^\perp} H^{\otimes n} \hat{O}_f$$

$$\hat{O}_f = \sum_x (-1)^{f(x)} |x\rangle\langle x|$$

$$U_s = H^{\otimes n} (2|0\dots 0\rangle\langle 0\dots 0| - I) H^{\otimes n}$$

$$= H^{\otimes n} U_{|0\rangle^\perp} H^{\otimes n}$$

With initial state:  $|\psi_{\text{ini}}\rangle = H^{\otimes n}|0\dots 0\rangle$

- Generalize above form to

$$\hat{G}_A = A U_{|\psi\rangle^\perp} A^{-1} \hat{O}_f$$

$$= U_{|\psi\rangle^\perp} \hat{O}_f$$

With initial state:  $|\psi\rangle = A|0\dots 0\rangle$

$$= \sin(\theta/2)|\psi_{\text{good}}\rangle + \cos(\theta/2)|\psi_{\text{bad}}\rangle$$

$|0\dots 0\rangle$  can contain extra work qubits

→ Action of  $G_A$  is a rotation of angle  $\theta$  in the 2D space spanned by  $\{|\psi_{\text{good}}\rangle, |\psi_{\text{bad}}\rangle\}$

Or equivalently  $\{|\psi\rangle, |\bar{\psi}\rangle \equiv \cos(\theta/2)|\psi_{\text{good}}\rangle - \sin(\theta/2)|\psi_{\text{bad}}\rangle\}$

$$(\hat{G}_A)^k |\psi\rangle = \sin(k\theta + \theta/2)|\psi_{\text{good}}\rangle + \cos(k\theta + \theta/2)|\psi_{\text{bad}}\rangle$$