

Reissner-Nordström Black Hole

$$ds^2 = - \underbrace{\left(1 - \frac{2GM}{r} + \frac{GQ^2}{r^2}\right)}_{\equiv \Delta(r)} dt^2 + \left(1 - \frac{2GM}{r} + \frac{GQ^2}{r^2}\right)^{-1} dr^2 + r^2 d\Omega^2$$

a.) compute energy-momentum tensor

$$G_{tt} = \frac{GQ^2}{r^4} \left(1 - \frac{2GM}{r} + \frac{GQ^2}{r^2}\right)$$

$$G_{rr} = -\frac{GQ^2}{r^4} \left(1 - \frac{2GM}{r} + \frac{GQ^2}{r^2}\right)^{-1}$$

$$G_{\theta t} = \frac{GQ^2}{r^2}$$

$$G_{\phi\phi} = \sin^2\theta G_{\theta\theta}$$

$$\Rightarrow \text{FTTG } T^0_0 = -\frac{GQ^2}{r^4}$$

recalling $E \in \mathcal{M}$ T^μ_ν from previous

$$\Rightarrow \vec{E} = \frac{Q}{r^2} \hat{r}$$

b.) Following the procedure from class.

radial null paths are $ds^2 = 0$ w/ $dt = \frac{dr}{\Delta(r)}$

coordinate singularities at $r_{\pm} = GM \pm \sqrt{G^2 M^2 + GQ^2}$

for $r > r_+$

$$\begin{aligned}
 -r_*(r) + r_{\infty} &= \int_r^{\infty} \frac{dr \cdot r^2}{(r-r_+)(r-r_-)} = \int_{r_+-r_-}^{\infty} \frac{r^2 dr}{r} \left[\frac{1}{r-r_+} - \frac{1}{r-r_-} \right] \\
 &= \frac{1}{r_+-r_-} \left[\frac{1}{2}(r^2 - 2rr_+ + r_+^2) + 2rr_+ - 2r_+^2 + r_+^2 \ln(r-r_+) \right. \\
 &\quad \left. - \frac{1}{2}(r^2 - 2rr_- + r_-^2) - 2rr_- + 2r_-^2 - r_-^2 \ln(r-r_-) \right]_{r_+-r_-}^{\infty} \\
 &= \frac{1}{r_+-r_-} \left[r(r_+-r_-) + r_+^2 \ln(r-r_+) - r_-^2 \ln(r-r_-) \right]_{r_+-r_-}^{\infty}
 \end{aligned}$$

$$\Rightarrow r_*(r) = r + \frac{r_+^2}{r_+-r_-} \ln(r-r_+) - \frac{r_-^2}{r_+-r_-} \ln(r-r_-)$$

for $r_- < r < r_+$

$$r_*(r) = r + \frac{r_+^2}{r_+-r_-} \ln(r_+-r) - \frac{r_-^2}{r_+-r_-} \ln(r-r_-)$$

$$0 < r < r_- \quad r_*(r) = r + \frac{r_+^2}{r_+-r_-} \ln(r_+-r) - \frac{r_-^2}{r_+-r_-} \ln(r_- - r)$$

OK so we can change coordinates to t, r_* and have

$$ds^2 = -\Delta(r) [dt^2 - dr_*^2] + r^2 d\Omega^2$$

and

$$e^{r_*} = e^{r + \frac{r_+^2}{r_+ - r_-} \ln|r - r_+| - \frac{r_-^2}{r_+ - r_-} \ln|r - r_-|}$$

$$= e^r |r - r_+|^{\frac{r_+^2}{r_+ - r_-}} |r - r_-|^{\frac{-r_-^2}{r_+ - r_-}}$$

$$= e^r \underbrace{|(r - r_+)(r - r_-)|^{\frac{r_+^2}{r_+ - r_-}}}_{\Delta(r) \times r^2} |r - r_-|^{\frac{-r_+^2 - r_-^2}{r_+ - r_-}}$$

$$\rightarrow \left(e^{r_* - r} |r - r_-|^{\frac{r_+^2 + r_-^2}{r_+ - r_-}} \right)^{\frac{r_+ - r_-}{r_+^2}} = r^2 |\Delta(r)|$$

$$\Delta(r) = \frac{1}{r^2} |r - r_-|^{\frac{r_+^2 + r_-^2}{r_+^2}} e^{\frac{r_+ - r_-}{r_+^2} (r_* - r)}$$

$$ds^2 = \underbrace{\frac{1}{r^2} |r - r_-|^{\frac{r_+^2 + r_-^2}{r_+^2}} e^{\frac{r_+ - r_-}{r_+^2} (r_* - r)}}_{\text{not singular as } r \rightarrow r_+} [dt^2 - dr_*^2]$$

(still singular as $r \rightarrow r_-$)

null radial paths given by $t \pm r_* = \text{const}$

change to coordinates $\xi_{\pm} = t \pm r_*$

then

$$ds^2 = -\frac{1}{r^2} (r - r_-) e^{\frac{r_+^2 + r_-^2}{r_+^2} \left(\xi_+ - \xi_- \right) - \frac{r_+ - r_-}{r^2} r} [d\xi_+ d\xi_-]$$

now, eliminate $\xi_{\pm}$ by changing to $U = -e^{-\frac{r_+ - r_-}{2r_+^2} \xi_-}$ $V = e^{\frac{r_+ - r_-}{2r_+^2} \xi_+}$

$$U = -e^{-\frac{r_+ - r_-}{2r_+^2} \xi_-}$$

$$V = e^{\frac{r_+ - r_-}{2r_+^2} \xi_+}$$

$$dU = +\frac{(r_+ - r_-)}{2r_+^2} e^{-\frac{r_+ - r_-}{2r_+^2} \xi_-} d\xi_- \quad dV = \frac{(r_+ - r_-)}{2r_+^2} e^{\frac{r_+ - r_-}{2r_+^2} \xi_+} d\xi_+$$

$$\rightarrow ds^2 = -\frac{1}{r^2} \left(\frac{2r_+^2}{r_+ - r_-} \right)^2 (r - r_-) e^{\frac{r_+^2 + r_-^2}{r_+^2} \left(\xi_+ - \xi_- \right) - \frac{r_+ - r_-}{r^2} r} dU dV$$

finally $T = \frac{U+V}{2}$ $R = \frac{V-U}{2}$

$r > r_+$

$$\leadsto ds^2 = -\frac{1}{r^2} \left(\frac{2r_+^2}{r_+ - r_-} \right)^2 (r - r_-) e^{\frac{r_+^2 + r_-^2}{r_+^2} \left(\xi_+ - \xi_- \right) - \frac{r_+ - r_-}{r^2} r} [-dT^2 + dR^2]$$

note for $r < r_+$

could use $\frac{r_+^2 + r_-^2}{r^2}$

$-(r_+ - r_-)r$

$$ds^2 = -\frac{1}{r^2} \left(\frac{2r_-^2}{r_+ - r_-} \right)^2 (r_+ - r) e^{\left[-dT^2 + dR^2 \right]}$$

$$\boxed{R^2 - T^2 = -UV = e^{\frac{r_+ - r_-}{2r_+^2} (\tilde{z}_+ - \tilde{z}_-)} = e^{\frac{r_+ - r_-}{2r_+^2} r}}$$

$$= e^{\frac{r_+ - r_-}{2r_+^2} r} \times \sqrt{|r - r_+|} |r - r_-|^{-\frac{r_-^2}{r_+^2}}$$

and

$$\boxed{t = \frac{1}{2}(\tilde{z}_+ + \tilde{z}_-) = \frac{1}{2} \left(\frac{-2r_+^2}{r_+ - r_-} \ln(|tV|) + \frac{2r_+^2}{r_+ - r_-} \ln V \right)}$$

$$= \frac{r_+^2}{r_+ - r_-} \ln \left(\frac{+V}{|V|} \right) = \frac{r_+^2}{r_+ - r_-} \ln \left(\frac{R+T}{R-T} \right)$$

can have $U, V \in (-\infty, \infty)$

how map to finite range to get penrose

e.g. $\tan\left(\frac{z \pm l}{2}\right) = \frac{T \pm R}{2r_+}$

spatial infinity $r \rightarrow \infty$, t - finite

$$\rightarrow \tan \frac{z+p}{2} \rightarrow \pm \infty \rightarrow \frac{z+p}{2} \rightarrow \frac{\pi}{2}$$

$$\frac{z+p}{2} \rightarrow \frac{-\pi}{2}$$

$$z \rightarrow 0 \quad p \rightarrow \pi$$

past null infinity $r \rightarrow \infty$, $t \rightarrow -\infty$ $r+t = \text{const}$

$$R-T \rightarrow \infty \Rightarrow \frac{z-p}{2} \rightarrow \frac{\pi}{2} \Rightarrow p = z - \pi$$

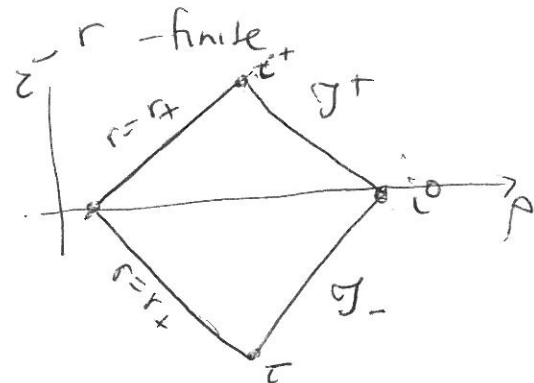
future null infinity $r \rightarrow \infty$ $t \rightarrow +\infty$ $r-t = \text{const}$

$$R+T \rightarrow \infty \Rightarrow p = \pi - z$$

past/future spatial infinity $t \rightarrow \pm \infty$

$$\begin{aligned} & z = \pi/2, \quad p = \pi/2 \\ \rightarrow & z = -\pi/2, \quad p = \pi/2 \end{aligned}$$

$$r \rightarrow r_+ \Rightarrow R^2 - T^2 = 0 \rightarrow \text{null}$$

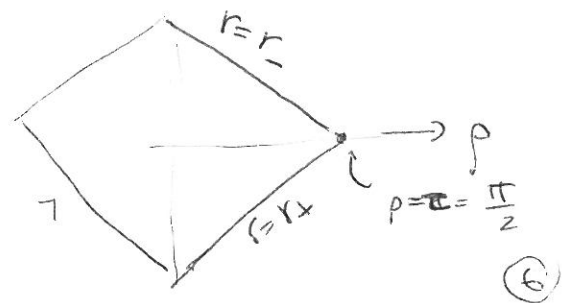


now
 $r \rightarrow r_- \Rightarrow R^2 - T^2 = 0 \rightarrow \text{null}$ but will have
 $v > 0$
 $u > 0$

$$\Rightarrow 0 < \frac{z+p}{2} < \frac{\pi}{2} \rightarrow \begin{aligned} z &> p \\ z &< \pi - p \end{aligned}$$

horizon at $r \rightarrow r_-$ at $z = \pi - p$

$\rightarrow$



(6)

Finally,

$$0 < r < r_+$$

$$= -UV$$

$$\frac{-r_-^2}{r_+^2}$$

$$r \rightarrow \infty$$

$$R^2 - T^2 = -|r_+| |r_-| < 0$$

singularity

timelike

$$r \rightarrow \frac{r_+^2}{r_+ - r_-} \ln r_+ - \frac{r_-^2}{r_+ - r_-} \ln r_-$$

$$U = r_+ e^{-\frac{r_+ - r_-}{2r_+^2} t} \left| r_- \right|^{\frac{r_-^2}{2r_+^2}}$$

$$V = r_+ e^{\frac{r_+ - r_-}{2r_+^2} t} \left| r_- \right|^{\frac{-r_-^2}{2r_+^2}}$$

$$= T - R$$

$$= T + R$$

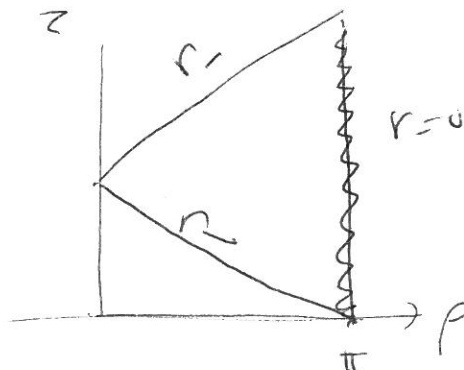
$$UV = r_+^2$$

$$T^2 - R^2 = r_+^2$$

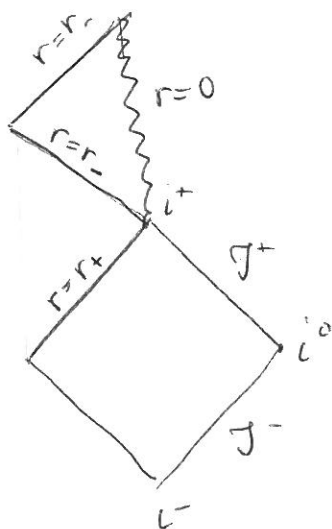
$$\tan \frac{z+p}{2} = T \sqrt{1 - \frac{r_-^2}{r_+^2}}$$

$$\tan \left(\frac{z-p}{2} \right) = \frac{1}{\tan \left(\frac{z+p}{2} \right)} \rightarrow \text{solved by } \rho = \frac{\pi}{2}$$

$$U, V > 0 \text{ as long as } \frac{3\pi}{2} < z < 2\pi$$



together



✓

d) show that coordinates (T, χ, θ, ϕ) with
 $\cosh z/l = \frac{1}{\cos T}$ make de Sitter metric conformal to
 $ds^2_{\text{Einstein-static}} = -dT^2 + d\chi^2 + \sin^2 \chi (d\theta^2 + \sin^2 \theta d\phi^2)$

w/ $\cosh z/l = \frac{1}{\cos T}$ $\frac{1}{l} \sinh z/l dz = \frac{-\sin T}{\cos^2 T} dT$

$$\Rightarrow \frac{1}{l^2} \sinh^2 z/l dz^2 = \frac{\sin^2 T}{\cos^4 T} dT^2$$

$$= \frac{1}{l^2} (\cosh^2 z/l - 1) dz^2$$

$$dz^2 = \cancel{l^2 \tan^2 T} \frac{l^2 \cot^2 T \cdot \tan^2 T}{\cos^2 T} dT^2$$

$$= \frac{1}{l^2} \left(\underbrace{\frac{1}{\cos^2 T}}_{\tan^2 T} - 1 \right)$$

$$\Rightarrow = \frac{l^2}{\cos^2 T} dT^2$$

→ our metric becomes

$$ds_4^2 = -\frac{l^2}{\cos^2 T} dT^2 + \frac{l^2}{\cos^2 T} [d\chi^2 + \sin^2 \chi d\theta^2 + \sin^2 \chi \sin^2 \theta d\phi^2]$$

$$= \frac{l^2}{\cos^2 T} [-dT^2 + d\chi^2 + \sin^2 \chi (d\theta^2 + \sin^2 \theta d\phi^2)]$$

$$\cosh z/l \in (0, \infty)$$

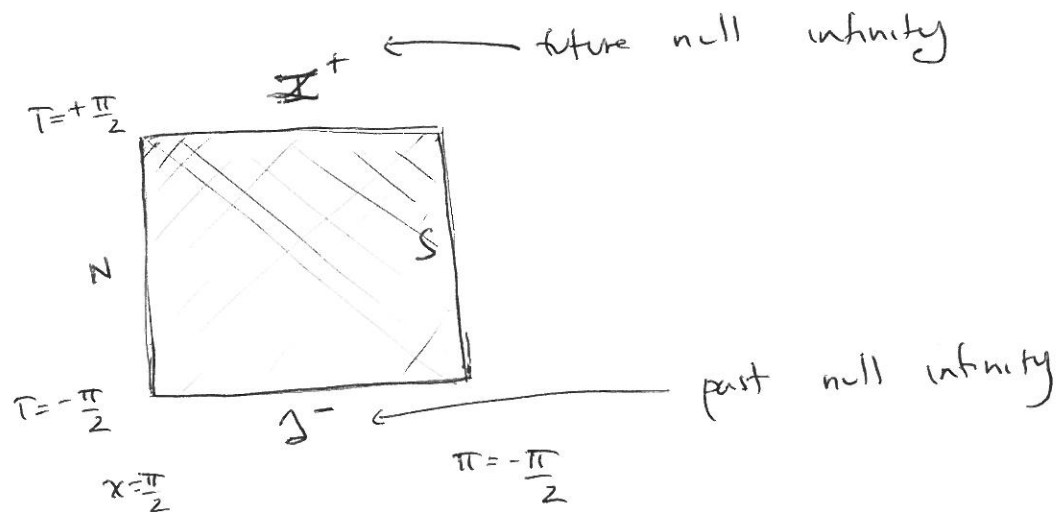
$$T \in (0, \pi/2)$$

$$z \in (-\infty, \infty) \Rightarrow T \in (-\pi/2, \pi/2)$$

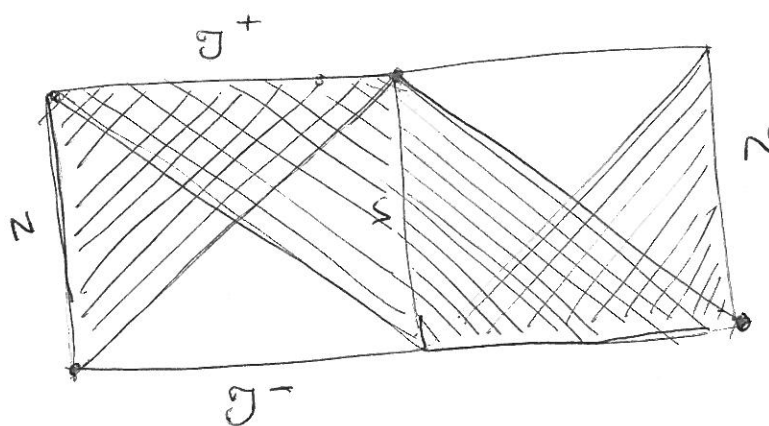
e.) use T, X coordinates for conformal diagram.

$X = -\pi/2$ south pole null geodesics on $T \pm X = \text{const}$

$X = +\pi/2$ north pole



note, we can add a copy on the other side of south pole S to understand causal structure (points that are reached by relations in $D(p)$).



causal part of future null infinity is shaded region does not cover all spacetime $\Rightarrow$ Horizon

- light ray: at north or south pole at I^- just makes it to opposite pole at I^+ .
- observer at either pole does not have access to entire spacetime. There